

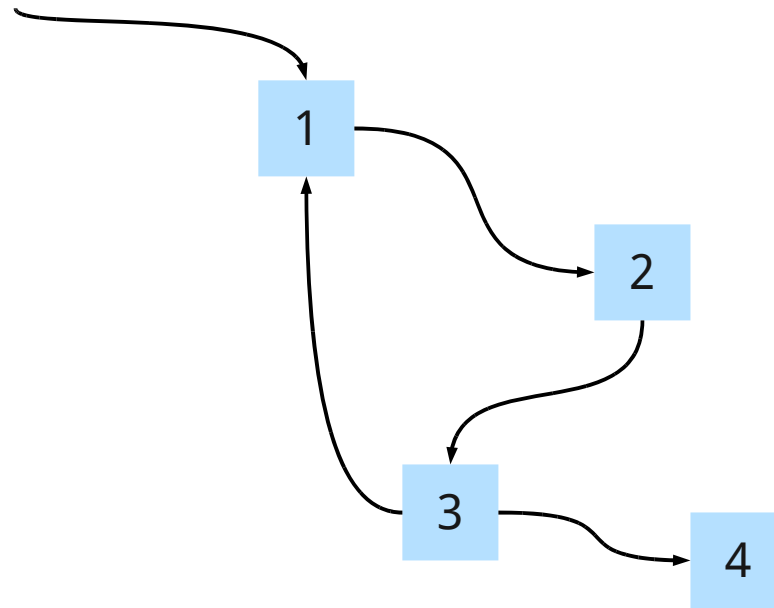
LLDSAL

A Low-Level Domain-Specific Aspect Language
for Dynamic Code-Generation and Program
Modification

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Motivation: program instrumentation

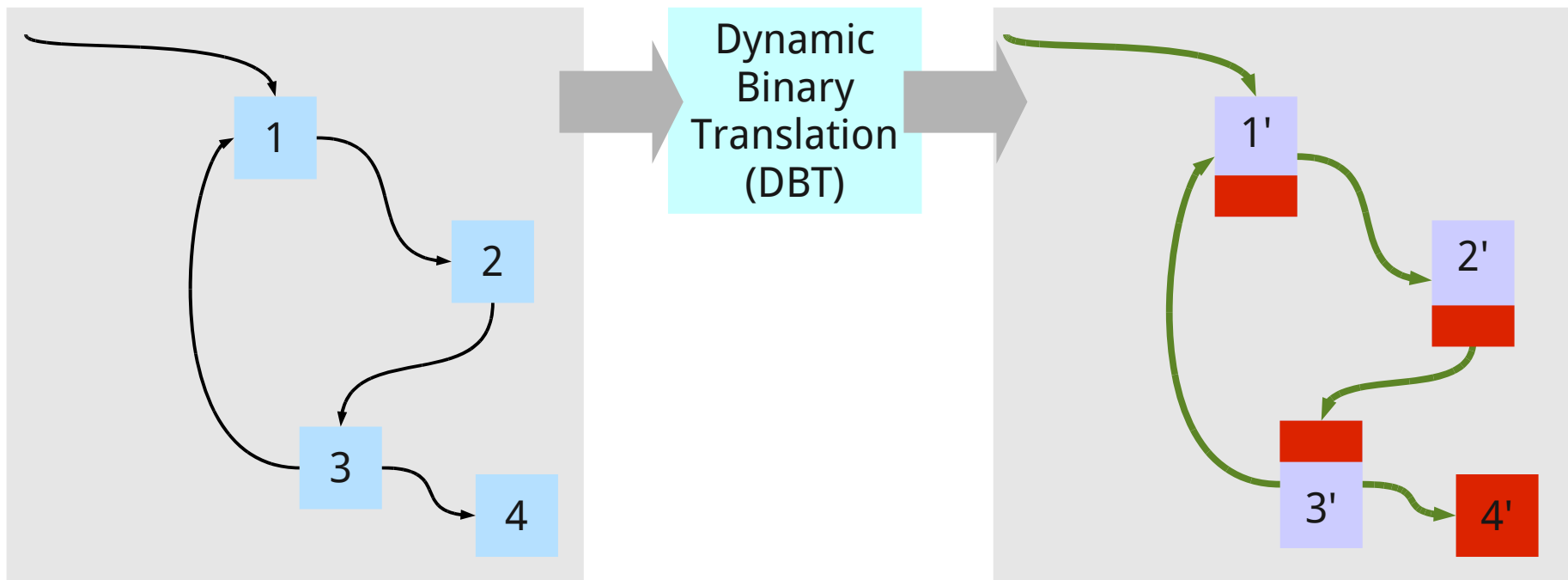
LLDSAL enables runtime code generation in a Dynamic Binary Translator (DBT)



Motivation: program instrumentation

LLDSAL enables runtime code generation in a Dynamic Binary Translator (DBT)

- **External aspects** extend program functionality
- **Internal aspects** to implement the instrumentation framework



Problem: code generation in DBT

DBT needs aspects that bridge between (translated) application and DBT world

- No calling conventions, must store everything
- Dynamic environment, no static addresses or locations
- Code must be fast (JIT-able)

```
char *code = ...;  
  
BEGIN_ASM (code)  
    addl $5, %eax  
    movl %eax, %edx  
    incl {&my_var}  
END_ASM
```

Solution: LLDSAL

Low-level Domain Specific Aspect/Assembly Language

- Aspects have access to high-level language constructs
- Aspects adhere to low-level conventions

DBT and LLDSAL enable AOP without any hooks

- JIT binary rewriting adds aspects on the fly

LLDSAL status: implemented and in use

- LLDSAL used for **internal aspects** of a BT (fastBT)
- LLDSAL guarantees **security properties** (libdetox security framework)

Outline

Motivation

Background: Binary Translation (BT)

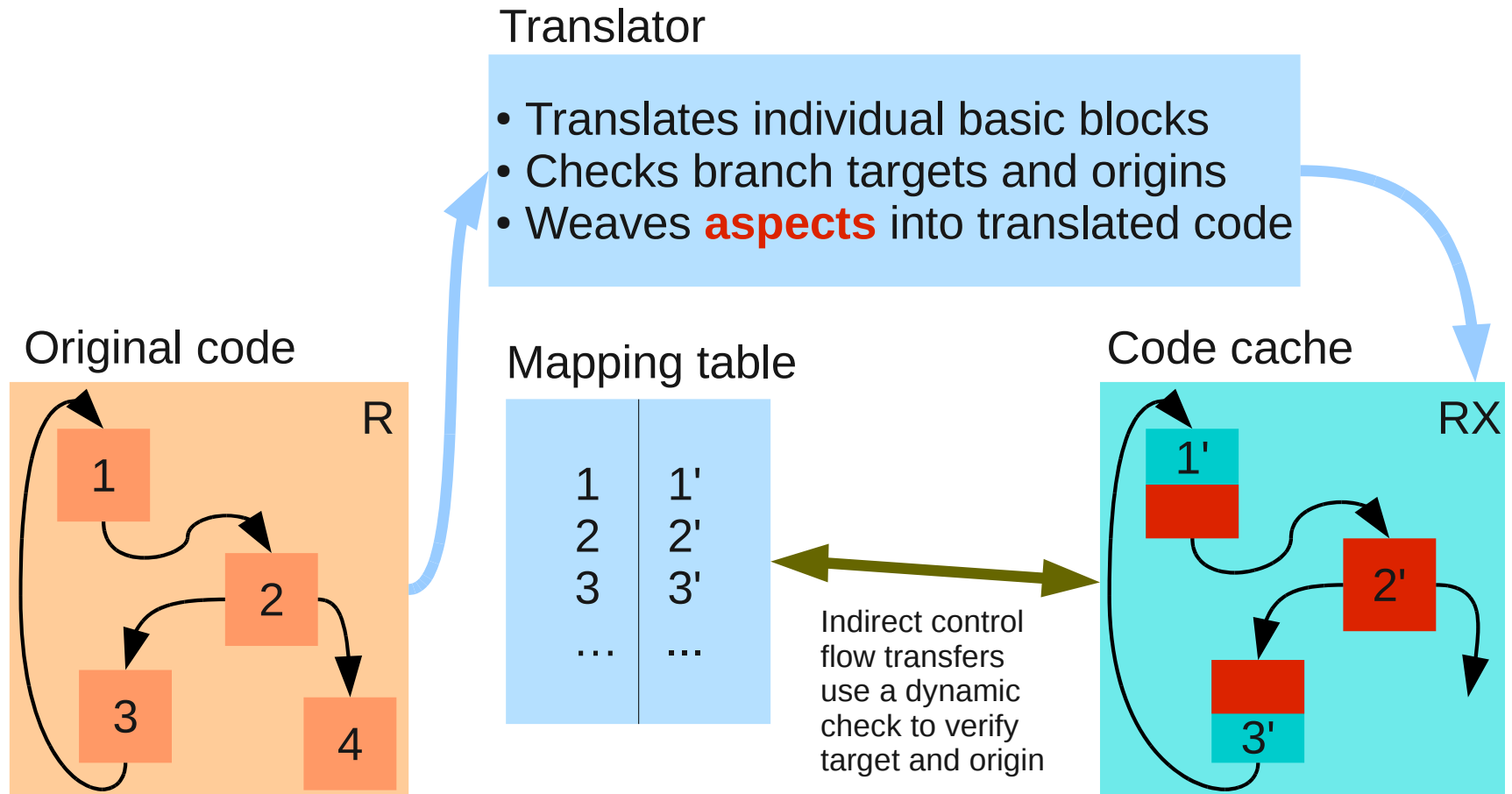
Language design

Implementation

Related work

Conclusion

Binary Translation in a nutshell



Outline

Motivation

Binary Translation (BT)

Language design

- Dynamic assembly language
- Data (variable) access
- Example: Dynamic code generation

Implementation

Related work

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Language design

Usability: low-level / high-level trade-off

- Mix assembly code plus access to high-level language constructs

Integration into host language

- DSL integrates naturally into the host language

No runtime dependencies

- Source-to-source translation (LLDSAL to C code)

LLDSAL defines a dynamic assembly language

- Enables dynamic low-level code generation at runtime

Dynamic assembly language

LLDSAL combines assembly code with access to high-level data structures

- Expressiveness and syntax comparable to inline assembler
- JIT code generation at runtime, optimization for data-accesses
- Parameters encoded (inlined) into instructions

Assembly block

```
char *code = ...;  
  
BEGIN_ASM(code)  
    addl $5, %eax  
    movl %eax, %edx  
    incl {&my_var}  
END_ASM
```

Pointer to code

Variable access

Comparison LLDSAL vs. inline asm

Code generation

- Inline asm **executes** code inline
- LLDSAL **generates** code inline

Access to dynamic or thread local data

- Inline asm uses **indirect memory references** (pointer chasing)
- LLDSAL embeds **direct pointers** in generated code

```
asm ("incl %0\n"  
    : "=a" (myvar)  
    : "0" (myvar))
```

```
char *code = ...;  
  
BEGIN_ASM(code)  
    addl $5, %eax  
    movl %eax, %edx  
    incl {&my_var}  
END_ASM
```

Data (variable) access

JIT-compiled code enables new data access patterns

- LLDSAL enables variable access in host space using `{variable}`

Variable addresses directly encoded in emitted code

- No parameters are passed
- No indirection or pointer chasing

```
// inside indirect_call action
BEGIN_ASM(code)
    incl {&tld->stat->nr_ind_calls}
END_ASM
```

Dynamic code generation

```
typedef void (*void_func) ();  
long my_func(long a) { return a * a; }
```

```
long result = 5;  
char *target = ...;  
void_func f = (void_func)target; {  
    BEGIN_ASM(target)  
        pushl ${result}           pushes $5 to the stack  
        call_abs {my_func}        my_func(5)  
        movl %eax, {&result}     result = my_func(5)  
        addl $4, %esp  
        ret  
    END_ASM  
} Execute dynamic code  
f(); // result == 25  
Clean-up and return
```

Outline

Motivation

Binary Translation (BT)

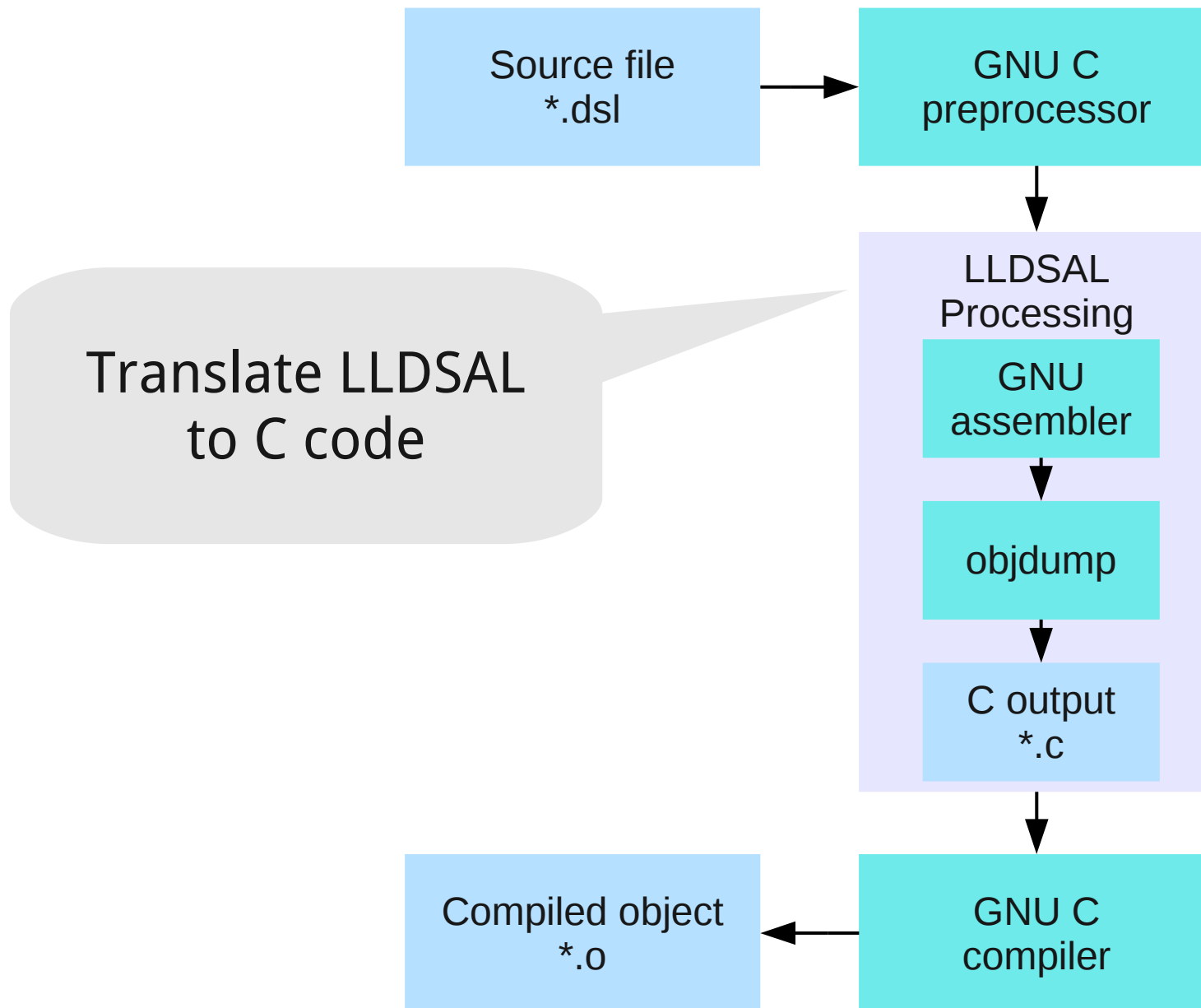
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LLDSAL implementation



LLDSAL alternatives

Macro-based approach

```
#define PUSHL_IMM32(dst, imm) \\  
    *dst++=0x68; *((int_32_t*)dst)=imm; dst+=4  
    ...  
PUSHL_IMM32(code, 0xdeadbeef);
```

- No additional compilation pass needed
- Error prone, manual encoding

JIT code generation (GNU lightning, asmjit)

- Very flexible, dynamic register allocation
- High overhead, library dependencies

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Related work

Compile-time DSL parsing [Porkolab et al., GPCE'10]

- LLDSAL first dynamic low-level DSAL for BT

Guyer and Lin describe an approach to optimize libraries for different environments [DSL'99]

- Annotation based, LLDSAL uses assembly code with high-level data access

Khepora is an approach to s2s DSLs [Faith et al., DSL'97]

- Full DSL parsing using syntax trees, too heavy-weight for LLDSAL

Conclusion

LLDSAL enables dynamic code generation for DBTs

- Direct access to host variables and data structures
- Low-overhead (no arguments passed, low-level encoding)
- No library dependencies

LLDSAL raises level of interaction between developer and BT framework

- Increased readability of code
- Better maintainability due to automatic translation

Thank you for your attention



Data (variable) access

Use the address of the variable $\${\&foo}$

- Instruction stores current address as immediate

Encode the (static) value of the variable $\${foo}$

- Instruction stores current value as immediate

Use dynamic value of variable $\{&foo\}$

- Instruction stores address of variable and encodes memory dereference

Use dynamic value of the address of the variable $\{foo\}$

- Instruction stores value as immediate and encodes memory dereference

Data (variable) access

```
pushl ${tld}
```

- Push current value of tld onto stack

```
movl {tld->stack-1}, %esp
```

- Read value from *(tld->stack-1) and store it in %esp

```
movl ${tld->stack-1}, %esp
```

- Store address of (tld->stack-1) in %esp

```
movl %eax, {&tld->saved_eax}
```

- Store %eax at &tld->saved_eax

Example (indirect lookup, inside BT)

```
BEGIN_ASM(transl_instr)
  pushfl
  pushl %ebx
  pushl %ecx

  movl 12(%esp), %ebx      // Load target address
  movl %ebx, %ecx         // Duplicate RIP

  /* Load hashline (eip element) */
  andl #{MAPPING_PATTERN >> 3}, %ebx;
  cmpl {tld->mappingtable}(, %ebx, 8), %ecx;
  jne nohit

hit:
  // Load target
  movl {tld->mappingtable+4}(, %ebx, 8), %ebx

  movl %ebx, {&tld->ind_target}
  popl %ecx
  popl %ebx
  popfl
  leal 4(%esp), %esp
  jmp *{&tld->ind_target}

nohit:
  // recover mode - there was no hit! ...
END_ASM
```